

**Modeling and Stability Analysis of SIQS Cholera Transmission Dynamics**Deepti Mokati<sup>1</sup>, V.H. Badshah<sup>1</sup> and Nirmala Gupta<sup>2</sup><sup>1</sup>School of Studies in Mathematics, Vikram University, Ujjain (M.P.), India<sup>2</sup>Govt. Girls P.G. College, Ujjain (M.P.), India**Abstract**

The present paper deals with a Susceptible-Infected-Quarantined-Susceptible mathematical model for cholera transmission dynamics. Find out disease-free and endemic equilibria and basic reproduction number  $R_q$ . Routh–Hurwitz criteria, Castillo-Chavez criteria and Dulac’s criterion plus Poincare-Bendixson theorem have been applied for analyzing stability for the considered model. Numerical simulations are also conceded.

**Keywords :** Quarantine, Reproduction number, Routh–Hurwitz criteria, Castillo-Chavez criteria.

**MSC :** 34D20, 49J15, 92D25, 92D30, 93D20.

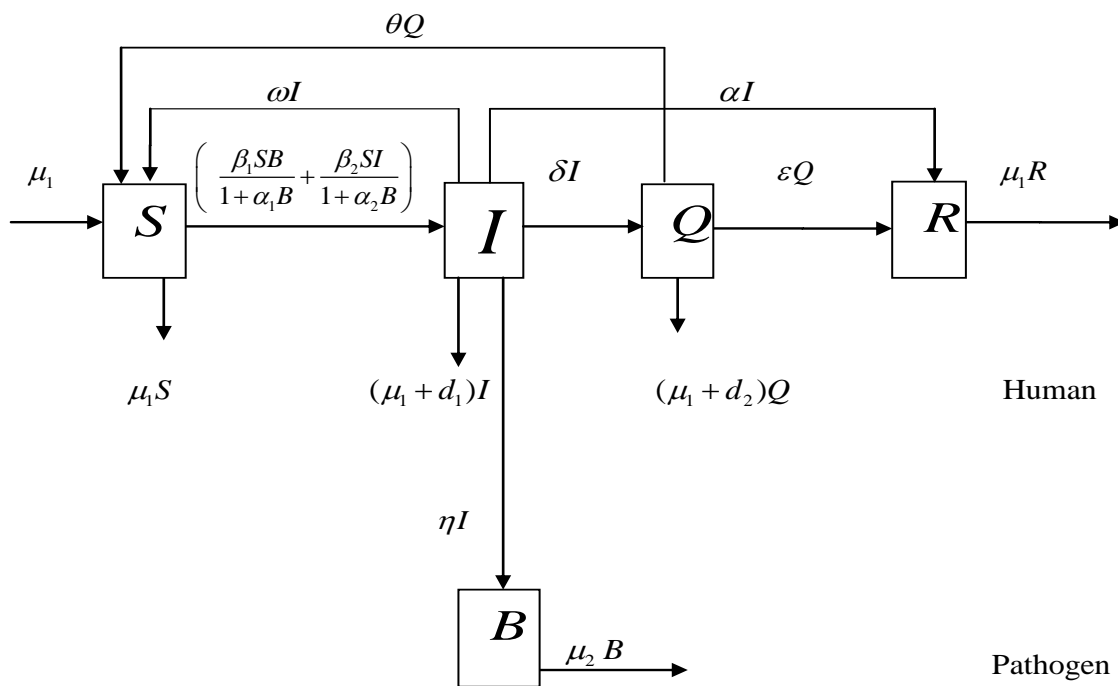
**1. Introduction**

Adebimpe O. et.al. [1] studied an SIQS epidemic model with saturated incidence rate and discussed the stability of disease-free and endemic equilibrium using different criterias. Castillo-Chavez et. al. discussed reproductive number and stability for some epidemic models. Specially, they gave a theorem on globally analysis of equilibrium points known as Castillo-Chavez criterion [2]. An SIS cholera epidemic model with quarantine effect have been developed by Mokati D. et al. [3]. Many researchers investigated the composite behavior of cholera disease. Nirwani N. et al. proposed a SIQR-B cholera epidemic model and gave the results about the effects of quarantine for the cholera model [4]. Pang Y. et al. discussed the dynamics of a stochastic SIQS outbreak model [5].

**2. The Mathematical model**

We have considered an SIQS cholera dynamical model in which human population is divided into susceptible ( $S$ ), infectious ( $I$ ), quarantine ( $Q$ ) and recovered ( $R$ ) individuals at time  $t$  and the pathogen population is assumed as  $B(t)$  at time  $t$ . Now consider the total number of population at time  $t$  is  $S+I+Q+R=I$ .

The following figure 1 represents the flow of individuals for the considered model :



**Figure 1 :** Transfer diagram for SIQS cholera model

The symbols are used here stands for

$\mu_1$  = Natural human birth and death rate,

$\beta_1, \beta_2$  = Contact rates for the human-environment & human-human interactions respectively ,

$\alpha_1, \alpha_2$  = Constant rates ,

$d_1, d_2$  = Disease related death rate constant in  $I$  &  $Q$  respectively,

$\alpha$  = Recovery rate from the disease ,

$\delta$  = Transmission rate between compartments  $I$  to  $Q$  ,

$\varepsilon$  = Transmission rate between compartments  $Q$  to  $R$  ,

$\eta$  = Rate of human contribution to the growth of the pathogen ,

$\mu_2$  = Death rate of the pathogen in the environment,

$\omega$  = Disease transmission rate from compartment  $I$  to  $S$  .

$\theta$  = Disease transmission rate between compartments  $Q$  to  $S$  .

All parameters are assumed nonnegative .

### 3. Mathematical Analysis of the model

The differential equations corresponding to the transfer diagram are

$$\begin{aligned}\frac{dS}{dt} &= \mu_1 + \omega I + \theta Q - \frac{\beta_1 S B}{1 + \alpha_1 B} - \frac{\beta_2 S I}{1 + \alpha_2 I} - \mu_1 S \\ \frac{dI}{dt} &= \frac{\beta_1 S B}{1 + \alpha_1 B} + \frac{\beta_2 S I}{1 + \alpha_2 I} - (d_1 + \mu_1 + \delta + \alpha + \omega) I \\ \frac{dQ}{dt} &= \delta I - (\varepsilon + d_2 + \mu_1 + \theta) Q \\ \frac{dR}{dt} &= \alpha I + \varepsilon Q - \mu_1 R \\ \frac{dB}{dt} &= \eta I - \mu_2 B\end{aligned}\quad (1)$$

The system (1) can also be considered in the form of system (2)

$$\begin{aligned}\frac{dS}{dt} &= \mu_1 + \omega I + \theta Q - \frac{\beta_1 S B}{1 + \alpha_1 B} - \frac{\beta_2 S I}{1 + \alpha_2 I} - \mu_1 S \\ \frac{dI}{dt} &= \frac{\beta_1 S B}{1 + \alpha_1 B} + \frac{\beta_2 S I}{1 + \alpha_2 I} - (d_1 + \mu_1 + \delta + \alpha + \omega) I \\ \frac{dQ}{dt} &= \delta I - (\varepsilon + d_2 + \mu_1 + \theta) Q \\ \frac{dB}{dt} &= \eta I - \mu_2 B\end{aligned}\quad (2)$$

The feasible region of human population  $D$  and pathogen  $\Omega$  corresponding to the system (2) will be

$$D = \{(S, I, Q) : S \geq 0, I \geq 0, Q \geq 0, S + I + Q \leq 1\}, \Omega = \{B : B \geq 0\} \text{ respectively.}$$

## 4. Equilibrium points

### 4.1 Disease-free equilibrium ( $E^0$ )

The system (2) can be written as

$$\begin{aligned}\mu_1 + \omega I + \theta Q - \frac{\beta_1 S B}{1 + \alpha_1 B} - \frac{\beta_2 S I}{1 + \alpha_2 I} - \mu_1 S &= 0 \\ \frac{\beta_1 S B}{1 + \alpha_1 B} + \frac{\beta_2 S I}{1 + \alpha_2 I} - (d_1 + \mu_1 + \delta + \alpha + \omega) I &= 0 \\ \delta I - (\varepsilon + d_2 + \mu_1 + \theta) Q &= 0 \\ \eta I - \mu_2 B &= 0\end{aligned}\quad (3)$$

Assume that  $I = 0$  (no disease), then  $Q = 0$  and  $B = 0$  and  $S = 1$ . Thus,  $E^0 = (1, 0, 0, 0)$ .

#### 4.2 Endemic equilibrium ( $E^*$ )

Assume that there is disease occurs ,then  $I \neq 0$  .

System (2) can be written as

$$\begin{aligned} \mu_1 + \omega I^* + \theta Q^* - \frac{\beta_1 S^* B^*}{1 + \alpha_1 B^*} - \frac{\beta_2 S^* I^*}{1 + \alpha_2 I^*} - \mu_1 S^* &= 0 \\ \frac{\beta_1 S^* B^*}{1 + \alpha_1 B^*} + \frac{\beta_2 S^* I^*}{1 + \alpha_2 I^*} - (d_1 + \mu_1 + \alpha + \delta + \omega) I^* &= 0 \end{aligned} \quad (4)$$

$$\delta I^* - (d_2 + \mu_1 + \varepsilon + \theta) Q^* = 0$$

$$\eta I^* - \mu_2 B^* = 0$$

$$\text{From equations third and fourth, we obtain } Q^* = \frac{\delta I^*}{(\varepsilon + \mu_1 + d_2 + \theta)}, \quad B^* = \frac{\eta I^*}{\mu_2}$$

respectively . On solving first and second equations ,we get

$$S^* = \frac{1}{\mu_1} \left[ \mu_1 - (d_1 + \mu_1 + \alpha + \delta) I^* + \frac{\theta \delta I^*}{(\varepsilon + \mu_1 + d_2 + \theta)} \right]$$

Again, from first equation,

$$\left\{ \left[ \frac{\beta_1 \eta}{\mu_2 + \alpha_1 \eta I^*} + \frac{\beta_2}{1 + \alpha_2 I^*} \right] \frac{1}{\mu_1} \left[ \mu_1 - (d_1 + \mu_1 + \alpha + \delta) I^* + \frac{\theta \delta I^*}{(\varepsilon + \mu_1 + d_2 + \theta)} \right] - (d_1 + \mu_1 + \alpha + \delta + \omega) \right\} I^* = 0.$$

But  $I^* \neq 0$  , so

$$\left\{ \left[ \frac{\beta_1 \eta}{\mu_2 + \alpha_1 \eta I^*} + \frac{\beta_2}{1 + \alpha_2 I^*} \right] \frac{1}{\mu_1} \left[ \mu_1 - (d_1 + \mu_1 + \alpha + \delta) I^* + \frac{\theta \delta I^*}{(\varepsilon + \mu_1 + d_2 + \theta)} \right] - (d_1 + \mu_1 + \alpha + \delta + \omega) \right\} = 0.$$

$$\text{Or } \frac{1}{\mu_1} \left[ \mu_1 - (d_1 + \mu_1 + \alpha + \delta) I^* + \frac{\theta \delta I^*}{(\varepsilon + \mu_1 + d_2 + \theta)} \right] = \frac{(d_1 + \mu_1 + \alpha + \delta + \omega)}{\left[ \frac{\beta_1 \eta}{\mu_2 + \alpha_1 \eta I^*} + \frac{\beta_2}{1 + \alpha_2 I^*} \right]} .$$

Take  $g_1(I^*) = g_2(I^*)$ , where

$$g_1(I^*) = \frac{1}{\mu_1} \left[ \mu_1 - (d_1 + \mu_1 + \alpha + \delta) I^* + \frac{\theta \delta I^*}{(\varepsilon + \mu_1 + d_2 + \theta)} \right] \text{ and } g_2(I^*) = \frac{(d_1 + \mu_1 + \alpha + \delta + \omega)}{\left[ \frac{\beta_1 \eta}{\mu_2 + \alpha_1 \eta I^*} + \frac{\beta_2}{1 + \alpha_2 I^*} \right]} .$$

Now, presume that  $I = I^*$  , then

$$g_1(I) = \frac{1}{\mu_1} \left[ \mu_1 - (d_1 + \mu_1 + \alpha + \delta)I + \frac{\theta \delta I}{(\varepsilon + \mu_1 + d_2 + \theta)} \right] \text{ and } g_2(I) = \frac{(d_1 + \mu_1 + \alpha + \delta + \omega)}{\left[ \frac{\beta_1 \eta}{\mu_2 + \alpha_1 \eta I} + \frac{\beta_2}{1 + \alpha_2 I} \right]}$$

If  $I = 0$ , then  $g_1(0) = 1$  and  $g_2(0) = \frac{\mu_2 (d_1 + \mu_1 + \alpha + \delta + \omega)}{(\beta_1 \eta + \beta_2 \mu_2)}$ .

If  $I > 0$  then  $g_1(I) < 0$  and  $g_2(I) > 0$ .

Then, we observe that  $g_2(I)$  is rising function for  $I \geq 0$ .

Hence, basic reproduction number  $R_q$  is given by  $R_q = \frac{(\beta_1 \eta + \beta_2 \mu_2)}{\mu_2 (d_1 + \mu_1 + \alpha + \delta + \omega)}$ .

If  $R_q > 1$ , then  $g_2(0) < 1$ .

Thus,  $E^* = \left( \frac{1}{\mu_1} \left[ \mu_1 - (d_1 + \mu_1 + \alpha + \delta)I^* + \frac{\theta \delta I^*}{(\varepsilon + \mu_1 + d_2 + \theta)} \right], I^*, \frac{\delta I^*}{\varepsilon + \mu_1 + d_2 + \theta}, \frac{\eta I^*}{\mu_2} \right)$ ,

where  $I^*$  can be find out on solving  $g_1(I^*) = g_2(I^*)$ .

## 5. Stability Analysis

**Theorem 1.** If  $R_q < 1$ , then the disease-free equilibrium is locally asymptotically stable.

**Proof.** Consider the matrix at disease-free equilibrium as

$$J(E^0) = \begin{bmatrix} -\mu_1 & \omega - \beta_2 & \theta & -\beta_1 \\ 0 & \beta_2 - (d_1 + \mu_1 + \delta + \alpha + \omega) & 0 & \beta_1 \\ 0 & \delta & -(\varepsilon + d_2 + \mu_1 + \theta) & 0 \\ 0 & \eta & 0 & -\mu_2 \end{bmatrix}$$

Then,

$$|J(E^0) - zI| = 0$$

$$\Rightarrow \begin{vmatrix} -\mu_1 - z & \omega - \beta_2 & \theta & -\beta_1 \\ 0 & \beta_2 - (d_1 + \mu_1 + \delta + \alpha + \omega + z) & 0 & \beta_1 \\ 0 & \delta & -(\varepsilon + d_2 + \mu_1 + \theta + z) & 0 \\ 0 & \eta & 0 & -\mu_2 - z \end{vmatrix} = 0.$$

On simplification, we have

$$(\varepsilon + d_2 + \mu_1 + \theta + z)(\mu_1 + z) \{ z^2 + (\mu_2 + d_1 + \mu_1 + \delta + \alpha + \omega - \beta_2)z + \mu_2 (d_1 + \mu_1 + \delta + \alpha + \omega) - (\mu_2 \beta_2 + \beta_1 \eta) \} = 0.$$

First two eigen values are  $z = -\mu_1 < 0$  and  $z = -(\varepsilon + \mu_1 + d_2 + \theta) < 0$ .

Remaining two eigen values are obtaining by the following equation

$z^2 + (\mu_2 + d_1 + \mu_1 + \delta + \alpha + \omega - \beta_2)z + \mu_2(d_1 + \mu_1 + \delta + \alpha + \omega) - (\mu_2\beta_2 + \beta_1\eta) = 0$ ,  
which can be written as

$$z^2 + a_1 z + a_2 = 0$$

where,

$$a_1 = (\mu_2 + d_1 + \mu_1 + \delta + \alpha + \omega - \beta_2),$$

$$a_2 = \mu_2(d_1 + \mu_1 + \delta + \alpha + \omega) - (\mu_2\beta_2 + \beta_1\eta) = \mu_2(d_1 + \mu_1 + \delta + \alpha + \omega) \left[ 1 - \frac{\mu_2\beta_2 + \beta_1\eta}{\mu_2(d_1 + \mu_1 + \delta + \alpha + \omega)} \right] \\ = 1 - R_q.$$

$$\text{where, } R_q = \frac{(\beta_1\eta + \beta_2\mu_2)}{\mu_2(d_1 + \mu_1 + \alpha + \delta + \omega)} < 1.$$

Hence,  $a_1 > 0, a_2 > 0$  and  $a_1 a_2 > 0$

Thus, by the Routh-Hurwitz criteria, the theorem is proved.

**Theorem 2.** The disease-free equilibrium is globally asymptotically stable if  $R_q < 1$ .

**Proof .** We employ method of Castillo-Chavez . System (1) can be consider into two

compartments, that is, uninfected and infected individuals, given by  $a_1: \frac{dU}{dt} = M(U, V)$

and  $a_2: \frac{dV}{dt} = P(U, V), P(U, 0) = 0$ , Where,  $U = (S, R) \in \mathbb{R}_+^2, V = (I, Q, B) \in \mathbb{R}_+^3$ .

$$\text{Let } E^0 = (N_0, 0), N_0 = \left( \frac{\pi}{\mu + \nu} \right). \quad (5)$$

Then  $E^0 = (N_0, 0)$  is globally asymptotically stable equilibrium of (5) if the following conditions are satisfied :

$b_1: E^0$  is globally asymptotically stable for  $\frac{dU}{dt} = M(U, 0), b_2: \hat{P}(U, V) \geq 0, (U, V) \in D$ ,

where  $P(U, V) = AV - \hat{P}(U, V)$ ,  $A$  is a Metzler matrix.

Then we can write  $A = F - V$ . Now,

$$\frac{dU}{dt} = M(U, V) = \begin{bmatrix} \pi - \frac{B\beta_e S}{k+B} - \beta_h SI - (\mu + \nu)S + \alpha Q \\ \nu S + \eta Q - \mu R \end{bmatrix} \text{ and } b_1: \frac{dU}{dt} = M(U, 0) = \begin{bmatrix} \pi - (\mu + \nu)S \\ \nu S \end{bmatrix}$$

$$\text{and } \frac{dV}{dt} = P(U, V) = \begin{bmatrix} \frac{B\beta_e S}{k+B} + \beta_h SI - (\mu + \delta_1 + \gamma) I \\ \gamma I - (\mu + \delta_2 + \eta + \alpha) Q \\ \varepsilon I - cB \end{bmatrix}, P(U, 0) = 0.$$

Hence,  $b_1$  is satisfied.

$$\text{Now for } b_2, A = F - V = \begin{bmatrix} \frac{\beta_h \pi}{\mu + \nu} - (\mu + \delta_1 + \gamma) & 0 & \frac{\beta_e \pi}{\mu + \nu} \\ \gamma & -(\mu + \delta_2 + \eta + \alpha) & 0 \\ \varepsilon & 0 & -c \end{bmatrix} \text{ and}$$

$$AV = \begin{bmatrix} \frac{\beta_h \pi}{\mu + \nu} - (\mu + \delta_1 + \gamma) & 0 & \frac{\beta_e \pi}{\mu + \nu} \\ \gamma & -(\mu + \delta_2 + \eta + \alpha) & 0 \\ \varepsilon & 0 & -c \end{bmatrix} \begin{bmatrix} I \\ Q \\ B \end{bmatrix} = \begin{bmatrix} \frac{\beta_h \pi I}{\mu + \nu} - (\mu + \delta_1 + \gamma) I + \frac{\beta_e \pi B}{\mu + \nu} \\ \gamma I - (\mu + \delta_2 + \eta + \alpha) Q \\ \varepsilon I - cB \end{bmatrix}$$

$$\text{Thus, } \hat{P}(U, V) = AV - P(U, V) = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} \hat{P}(U, V)_1 \\ \hat{P}(U, V)_2 \\ \hat{P}(U, V)_3 \end{bmatrix}. \text{ Hence, } b_2 \text{ is satisfied.}$$

This completes the proof.

**Theorem 3.** If  $R_q > 1$ , then the endemic equilibrium is locally asymptotically stable.

**Proof.** The variational matrix will be

$$J(E^*) = \begin{bmatrix} \frac{-\beta_1 B^*}{1 + \alpha_1 B^*} - \frac{\beta_2 I^*}{1 + \alpha_2 I^*} - \mu_1 & \omega - \frac{\beta_2 S^*}{(1 + \alpha_2 I^*)^2} & \theta & \frac{-\beta_1 S^*}{(1 + \alpha_1 B^*)^2} \\ \frac{\beta_1 B^*}{1 + \alpha_1 B^*} + \frac{\beta_2 I^*}{1 + \alpha_2 I^*} & \frac{\beta_2 S^*}{(1 + \alpha_2 I^*)^2} - (d_1 + \mu_1 + \delta + \alpha + \omega) & 0 & \frac{\beta_1 S^*}{(1 + \alpha_1 B^*)^2} \\ 0 & \delta & -(\varepsilon + d_2 + \mu_1 + \theta) & 0 \\ 0 & \eta & 0 & -\mu_2 \end{bmatrix}.$$

$$\text{Or } J(E^*) = \begin{bmatrix} -J_1 - \mu_1 & \omega - J_2 & \theta & -J_3 \\ J_1 & K & 0 & J_3 \\ 0 & \delta & -L & 0 \\ 0 & \eta & 0 & -\mu_2 \end{bmatrix}$$

where,

$$J_1 = \frac{\beta_1 B^*}{1 + \alpha_1 B^*} + \frac{\beta_2 I^*}{1 + \alpha_2 I^*}, \quad J_2 = \frac{\beta_2 S^*}{(1 + \alpha_2 I^*)^2}, \quad J_3 = \frac{\beta_1 S^*}{(1 + \alpha_1 B^*)^2},$$

$$K = J_2 - (d_1 + \mu_1 + \alpha + \delta + \omega) \text{ and } L = (\varepsilon + \mu_1 + d_2 + \theta).$$

Then,

$$|J(E^*) - \lambda I| = 0.$$

$$\Rightarrow J(E^*) = \begin{vmatrix} -J_1 - \mu_1 - \lambda & \omega - J_2 & \theta & -J_3 \\ J_1 & K - \lambda & 0 & J_3 \\ 0 & \delta & -(L + \lambda) & 0 \\ 0 & \eta & 0 & -\mu_2 - \lambda \end{vmatrix} = 0.$$

On simplification,

$$\begin{aligned} & \lambda^4 + \lambda^3(-K + L + \mu_2 + J_1 + \mu_1) + \lambda^2(-K\mu_2 - KL - K(J_1 + \mu_1) + (J_1 + \mu_1)\mu_2 + \mu_2L + (J_1 + \mu_1)L - J_3\eta + J_1\omega - J_1J_2) \\ & + \lambda((J_1 + \mu_1)\{-K(\mu_2 + L) + \mu_2L - J_3\eta\} - K\mu_2L - J_3\eta L + J_1\{\omega(\mu_2 + L) - J_2(\mu_2 + L) - J_3\eta + \theta\delta\}) \\ & + (J_1\omega\mu_2L + J_1\theta\delta\mu_2 - J_1J_2\mu_2L - J_1J_3\eta L - (J_1 + \mu_1)LK\mu_2 - (J_1 + \mu_1)J_3\eta L) = 0. \end{aligned}$$

or

$$\lambda^4 + a_1\lambda^3 + a_2\lambda^2 + a_3\lambda + a_4 = 0$$

where

$$a_1 = (-K + L + \mu_2 + J_1 + \mu_1) = 3\mu_1 + (d_1 + \delta + \alpha + \omega + \varepsilon + d_2 + \theta) + \mu_2 + J_1 - J_2 > 0$$

$$\begin{aligned} a_2 &= (-K\mu_2 - KL - K(J_1 + \mu_1) + (J_1 + \mu_1)\mu_2 + \mu_2L + (J_1 + \mu_1)L - J_3\eta + J_1\omega - J_1J_2) \\ &= (J_1 + \mu_1)(2\mu_1 + d_1 + \delta + \alpha + \omega + \varepsilon + d_2 + \theta + \mu_2 - J_2) - (J_2 - (\mu_1 + d_1 + \delta + \alpha + \omega))(\varepsilon + d_2 + \theta + \mu_2 + \mu_1) \\ &\quad + \mu_2(\varepsilon + d_2 + \theta + \mu_1) - J_3\eta + J_1\omega - J_1J_2 > 0 \end{aligned}$$

$$\begin{aligned} a_3 &= ((J_1 + \mu_1)\{-K(\mu_2 + L) + \mu_2L - J_3\eta\} - K\mu_2L - J_3\eta L + J_1\{\omega(\mu_2 + L) - J_2(\mu_2 + L) - J_3\eta + \theta\delta\}) \\ &= (J_1 + \mu_1)\{-(J_2 - (\mu_1 + d_1 + \delta + \alpha + \omega))(\varepsilon + d_2 + \theta + \mu_2 + \mu_1) + \mu_2(\varepsilon + d_2 + \theta + \mu_1) - J_3\eta\} \\ &\quad - \mu_2(J_2 - (\mu_1 + d_1 + \delta + \alpha + \omega))(\varepsilon + d_2 + \theta + \mu_1) - J_3\eta(\varepsilon + d_2 + \theta + \mu_1) + J_1\{\omega(\mu_2 + \varepsilon + d_2 + \theta + \mu_1) \\ &\quad - J_2(\mu_2 + \varepsilon + d_2 + \theta + \mu_1)J_3\eta + \theta\delta\} > 0 \end{aligned}$$

$$\begin{aligned} a_4 &= (J_1\omega\mu_2L + J_1\theta\delta\mu_2 - J_1J_2\mu_2L - J_1J_3\eta L - (J_1 + \mu_1)LK\mu_2 - (J_1 + \mu_1)J_3\eta L) \\ &= J_1\omega\mu_2(\varepsilon + d_2 + \theta + \mu_1) + J_1\theta\delta\mu_2 - J_1J_2\mu_2(\varepsilon + d_2 + \theta + \mu_1) - J_1J_3\eta(\varepsilon + d_2 + \theta + \mu_1) \\ &\quad - (J_1 + \mu_1)\mu_2(\varepsilon + d_2 + \theta + \mu_1)(J_2 - (\mu_1 + d_1 + \delta + \alpha + \omega)) - (J_1 + \mu_1)J_3\eta(\varepsilon + d_2 + \theta + \mu_1) > 0 \end{aligned}$$

It is clearly seen that  $a_1 > 0$ ,  $a_2 > 0$ ,  $a_3 > 0$ ,  $a_4 > 0$  and  $a_1a_2a_3 > a_3^2 + a_1^2a_4$ . Hence, by

Routh-Hurwitz criteria, the theorem is proved.

**Theorem 4.** The endemic equilibrium is globally asymptotically stable if  $R_q > 1$ .

**Proof.** Assume



$$F_1 = \pi - \frac{B\beta_e S}{k+B} - \beta_h SI - (\mu + \nu)S + \alpha Q$$

$$F_2 = \frac{B\beta_e S}{k+B} + \beta_h SI - (\mu + \delta_1 + \gamma) I$$

$$F_3 = \gamma I - (\mu + \delta_2 + \eta + \alpha) Q$$

$$F_4 = \nu S + \eta Q - \mu R$$

$$F_5 = \varepsilon I - cB$$

We use Dulac plus Poincare Bendixson theorem as follows

Consider ,  $H(S, I, Q, R, B) = \frac{1}{SIQRB}$  where  $S > 0, I > 0, Q > 0, R > 0, B > 0$ .

$$\text{Then , } \nabla(HF) = \frac{\partial}{\partial S}(H.F_1) + \frac{\partial}{\partial I}(H.F_2) + \frac{\partial}{\partial Q}(H.F_3) + \frac{\partial}{\partial R}(H.F_4) + \frac{\partial}{\partial B}(H.F_5)$$

$$\Rightarrow \nabla(HF) = \frac{-\pi}{S^2 I Q R B} - \frac{\alpha}{S^2 I R B} - \frac{\beta_e}{I^2 Q R (k+B)} - \frac{\gamma}{S Q^2 R B} - \frac{\nu}{I Q R^2 B} - \frac{\eta}{S I R^2 B} - \frac{\varepsilon}{S Q R B^2} < 0.$$

Hence, by Dulac's criterion , The proof is completed.

## 6. Numerical Simulation and graphical representation

**Case I :** Disease dies out at  $R_q < 1$

$S(0) = 80000, I(0) = 60000, Q(0) = 40000, R(0) = 20000, B(0) = 200000,$   
 $\mu_1 = 9.13 \times 10^{-5} / \text{day}, \beta_1 = 0.00025 / \text{day}, \alpha_1 = 5 \text{ days}, \beta_2 = 0.00015 / \text{day},$   
 $\alpha_2 = 10 \text{ days}, d_1 = 0.015 / \text{day}, \alpha = 0.2 / \text{day}, \delta = 0.005 / \text{day}, \varepsilon = 0.2 / \text{day},$   
 $d_2 = 0.0001 / \text{day}, \eta = 10 \text{ cells} / \text{litre} / \text{day} / \text{person}, \mu_2 = 0.33 / \text{day}, \omega = 0.2 / \text{day},$   
 $\theta = 0.4, R_q = 0.018 < 1.$

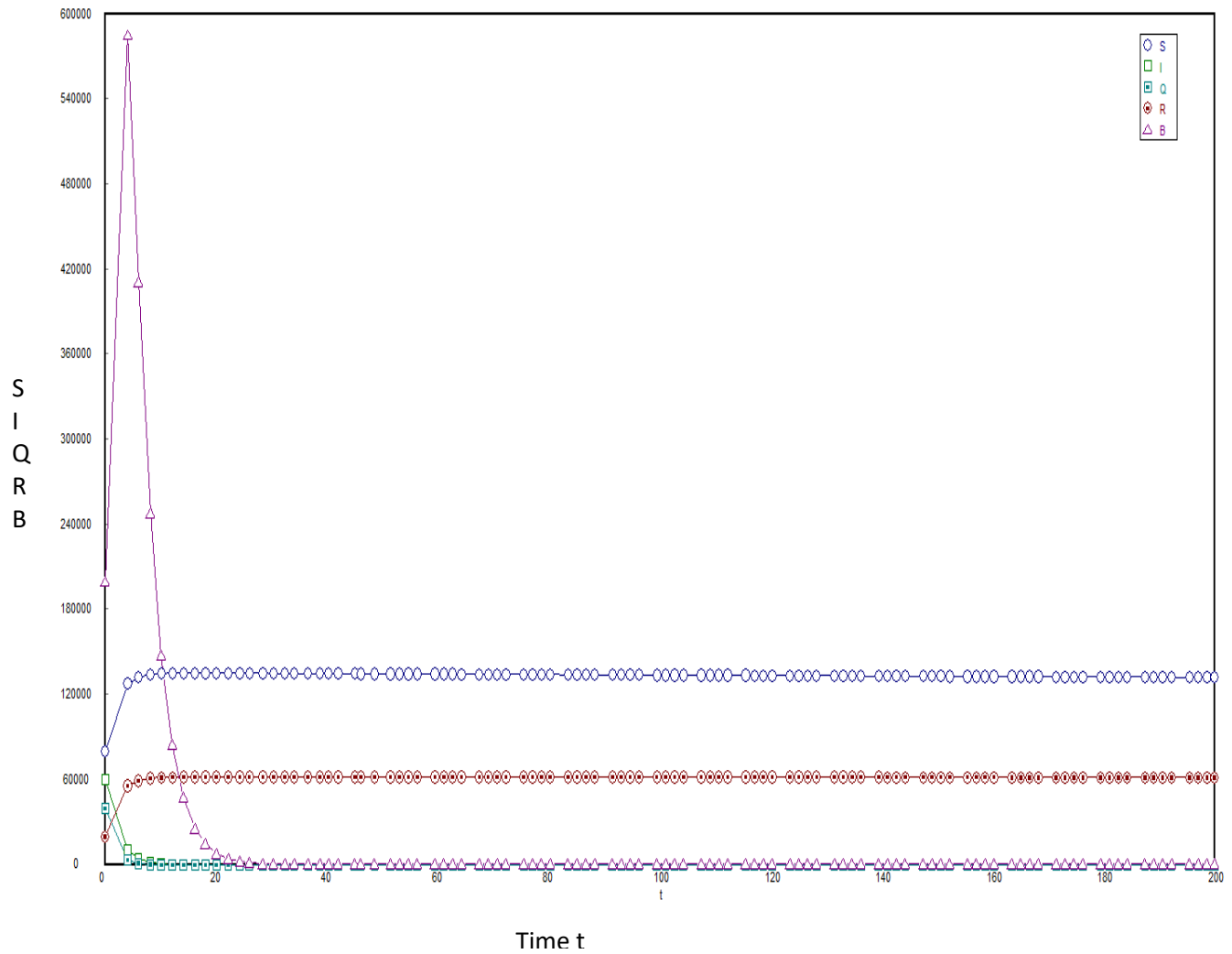


Figure 2 SIQS cholera transmission model when  $R_q < 1$  .

Case II : Disease persists at  $R_q > 1$

$S(0) = 80000, I(0) = 20000, Q(0) = 40000, R(0) = 50000, B(0) = 200000,$   
 $\mu_1 = 9.13 \times 10^{-5} / \text{day}, \beta_1 = 0.25 / \text{day}, \alpha_1 = 5 \text{ days}, \beta_2 = 0.0015 / \text{day},$   
 $\alpha_2 = 10 \text{ days}, d_1 = 0.002 / \text{day}, \alpha = 0.00002 / \text{day}, \delta = 0.5 / \text{day}, \varepsilon = 0.2 / \text{day},$   
 $d_2 = 0.0001 / \text{day}, \eta = 10 \text{ cells / litre / day / person}, \mu_2 = 0.33 / \text{day}, \omega = 0.9 / \text{day},$   
 $\theta = 0.8, R_q = 5.404 > 1.$

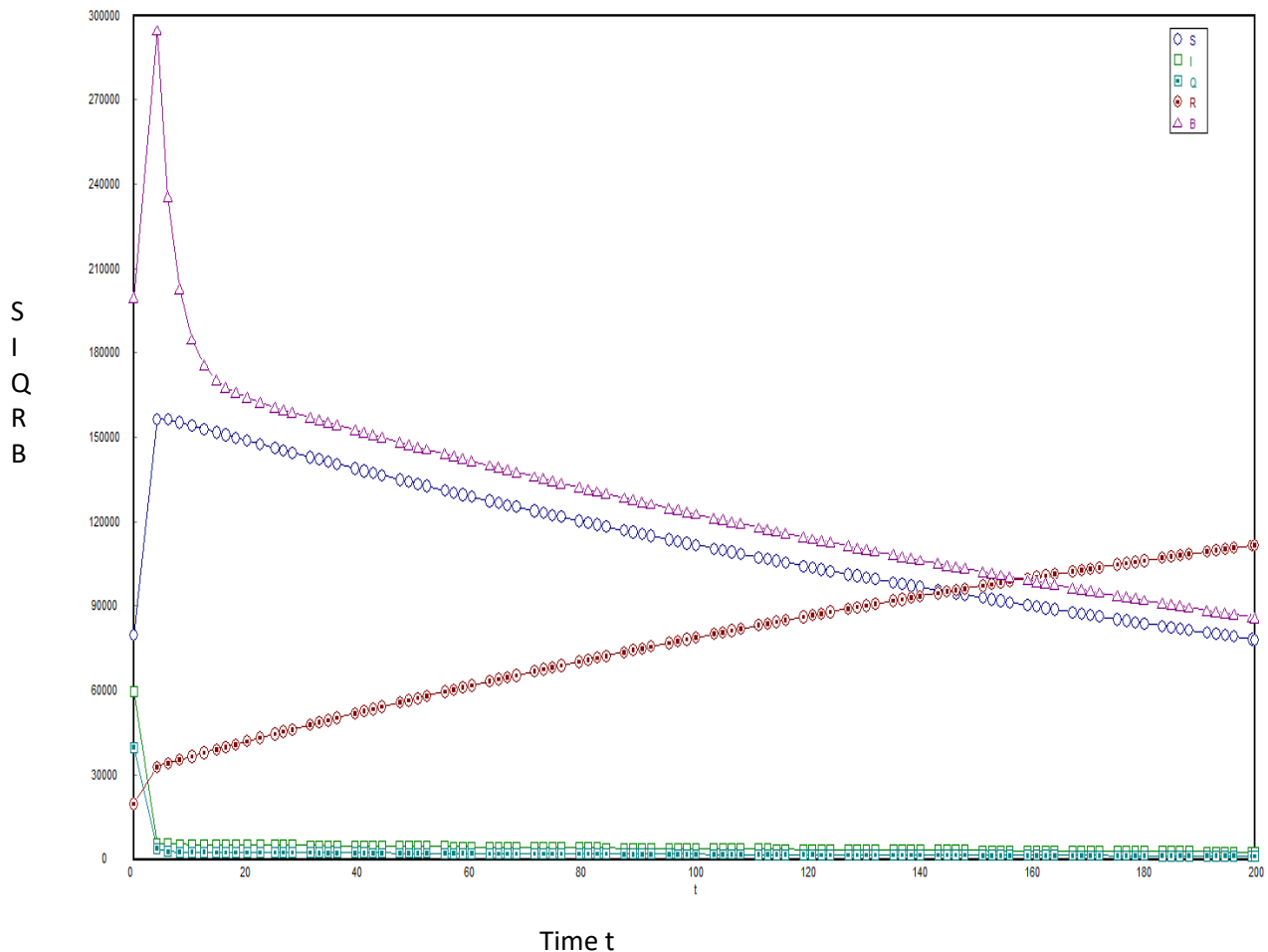


Figure 3 SIQS cholera transmission model when  $R_q > 1$

## 7. Conclusion

In this paper, we have discussed asymptotic behavior for an SIQS cholera epidemic model mathematically and numerically. We have obtained disease-free and endemic equilibria for the model and analyzed the stability criteria for the both equilibria. Mathematically, we have concluded that if basic reproduction number  $R_q < 1$ , then the disease-free equilibrium is local and global asymptotic stable using Routh-Hurwitz criteria and Castillo-Chavez criteria respectively. If basic reproduction number  $R_q > 1$ , then the endemic equilibrium is local and

global asymptotic stable using Routh-Hurwitz criteria and Dulac's plus Poincare criteria respectively .Numerically calculations have been done . Plot graphs of  $SIQRB$  vs time  $t$  which give more clarity when the disease dies out and when the disease persists .

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